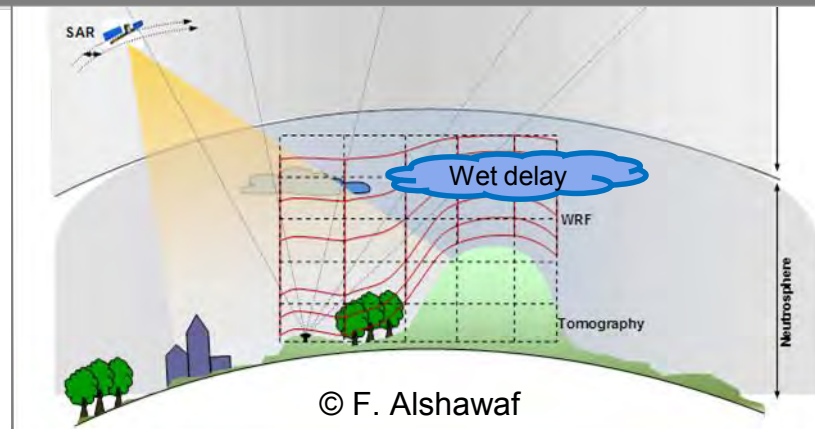


# Comparison of wet phase delay estimates derived from GNSS, InSAR, and MERIS data

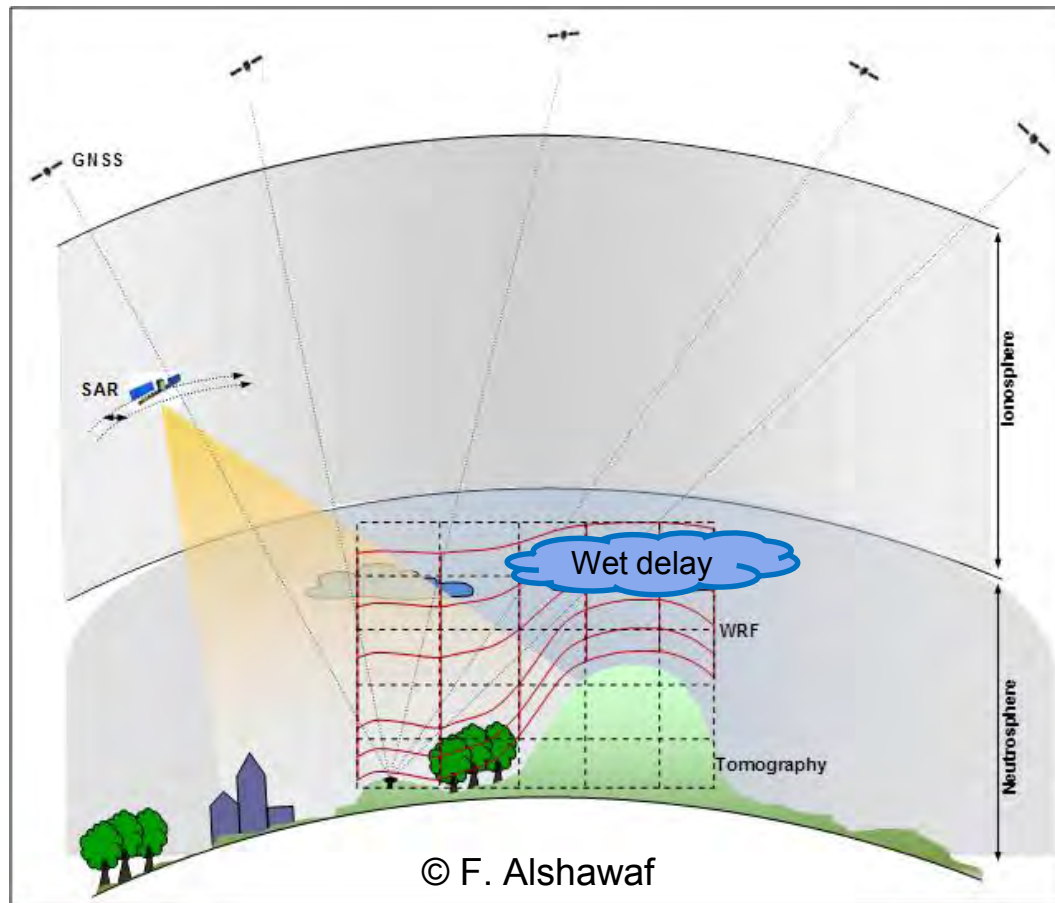


Institute of Photogrammetry and Remote Sensing and Geodetic Institute, Department of Civil Engineering, Geo and Environmental Sciences  
Earth Observation Center at the German Aerospace Center



Master Thesis

# Motivation



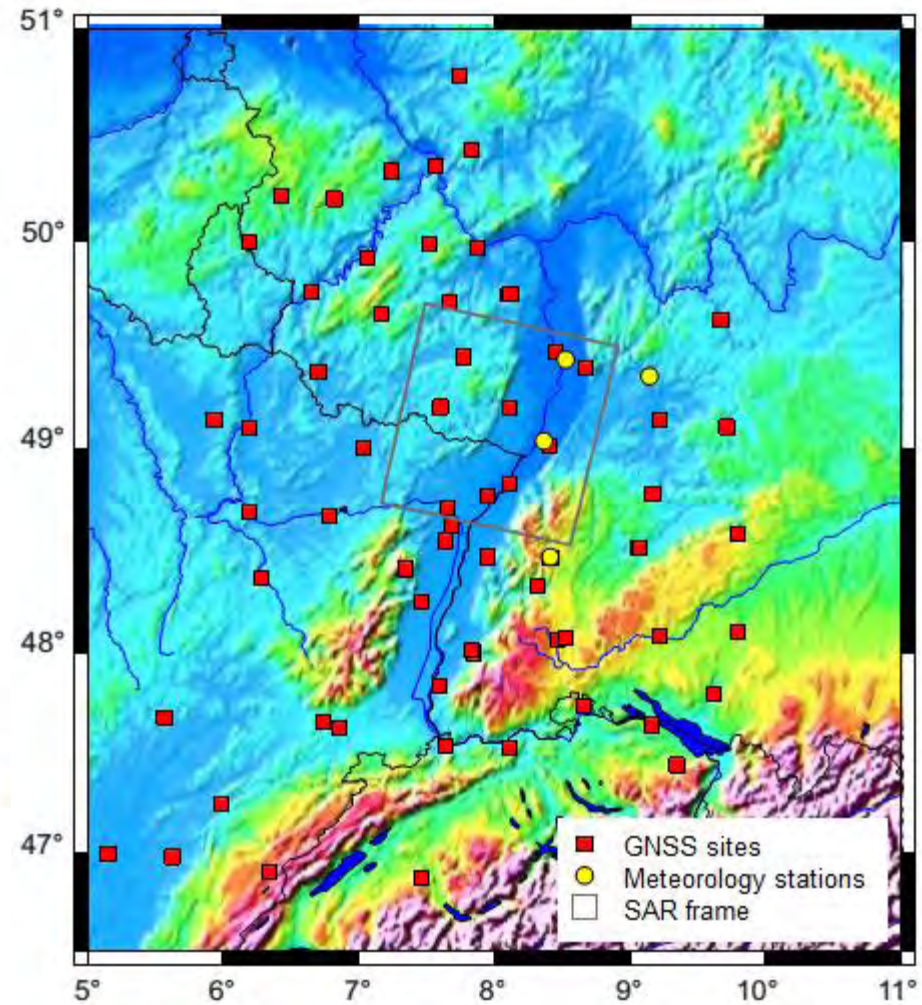
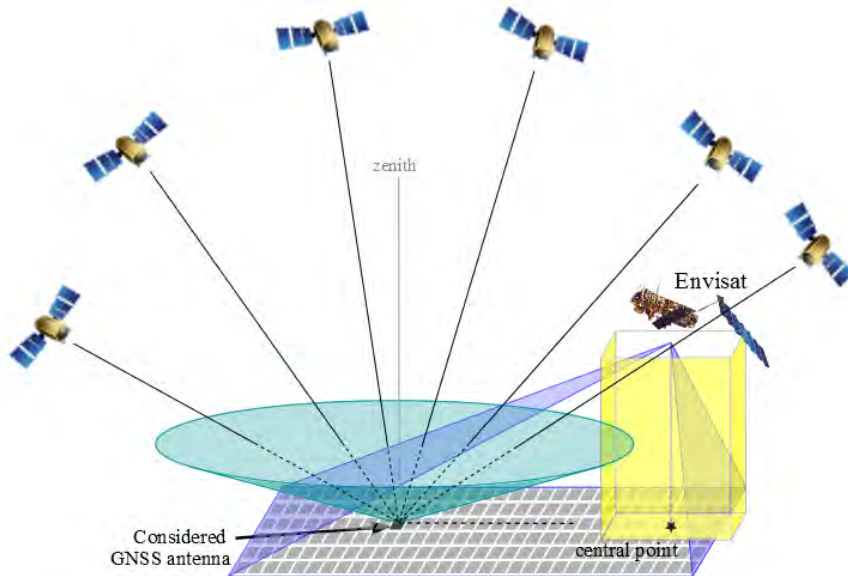
## Water vapor

- Key element in
  - Meteorology
  - Climatology
- Error source in
  - GNSS
  - InSAR
- Highly variable in
  - Time
  - Space

HydroKIT:            Exploitation of geodetic sensors  
                           Reconstruction of our Earth's atmosphere

# Database

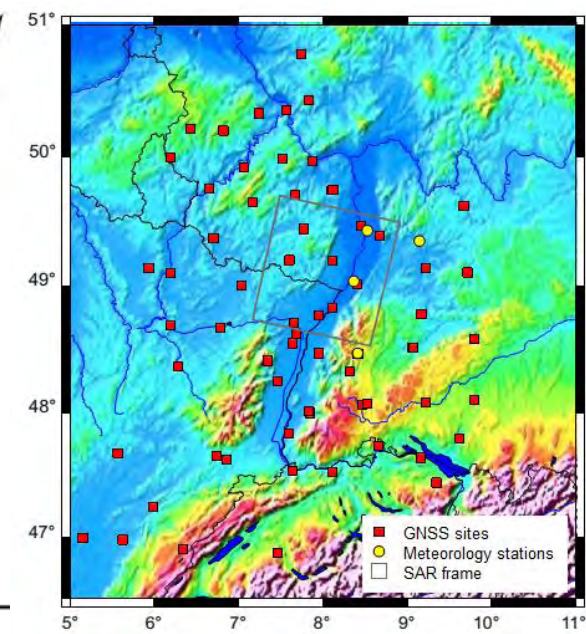
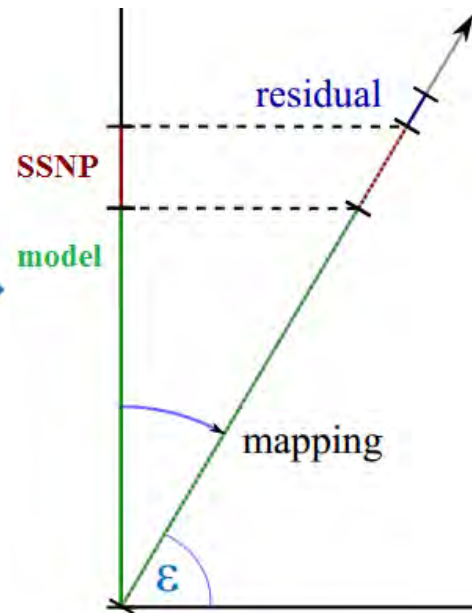
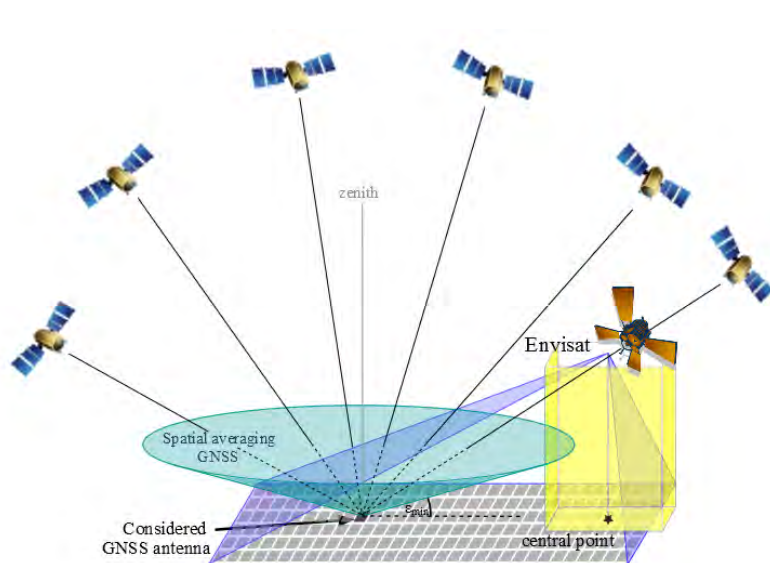
- **GNSS (PPP)**  
inter-site distance: 40-60 km
- **PS-InSAR (from Envisat)**  
SAR frame  $\approx 100 \times 100 \text{ km}^2$
- **MERIS (reference)**  
resolution of  $300 \times 300 \text{ m}^2$



**Study region: Upper Rhine Graben**

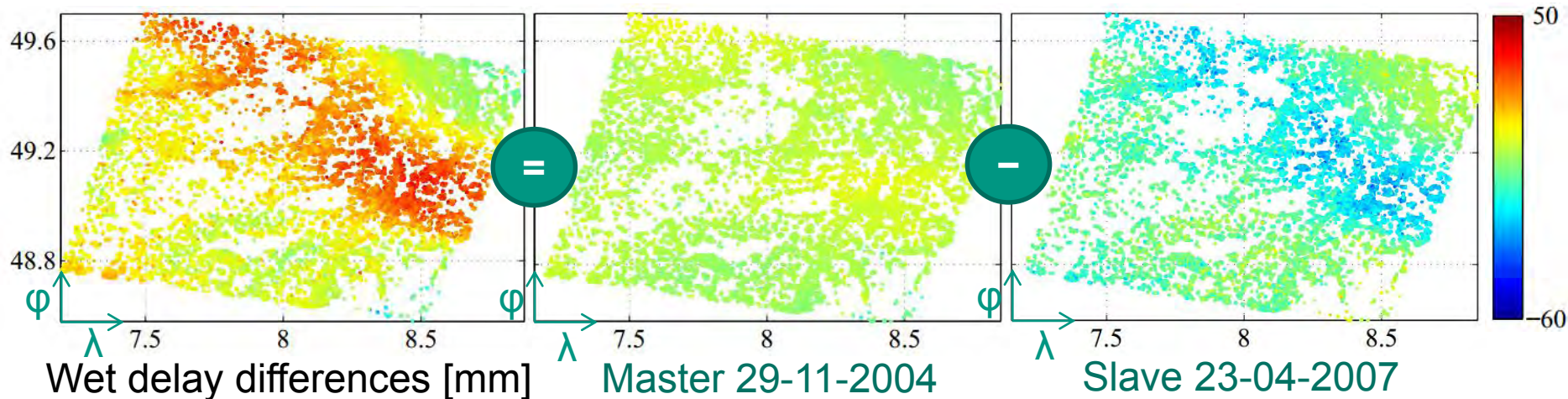
# Sensor Characteristics


	Spatial resolution	Temporal resolution	Observation geometry	Deduced delay
<b>GNSS</b>	-	++	point-wise	total integrated
<b>PS-InSAR</b>	++	-	laminar	short-scale integrated wet
<b>MERIS</b>	+++	-	column-wise	integrated wet



# Wet Delay from InSAR

Measured:  $\Phi_{\text{slave}} - \Phi_{\text{master}} \hat{=} \Delta_{\text{master}} - \Delta_{\text{slave}}$



- **Partial** wet delays without
  - Topography-dependent part
  - Linear trend
- Inversion yields phases per acquisition  small # of acquisitions
- Conversion from phase to delay  $\Delta_{acq_i}^{slant} = -\phi \cdot \frac{\lambda}{4\pi}$

## Master Selection: Approach of Hooper (2007)

Master acquisition:

- Sum of decorrelation  $\rightarrow$  min
- Sum of correlation  $\rightarrow$  max

Correlation:

$$\rho = \rho_{temporal} \cdot \rho_{spatial} \cdot \rho_{doppler} \cdot \rho_{thermal}$$

thermal noise  
(assumed to  
be constant)

temporal  
baseline  $B_{temp}$

perpendicular  
baseline  $B_{\perp}$

difference  $\Delta DC$  in  
Doppler centroid

Maximal baselines in our case:

$$B_{temp} \approx 4 \text{ years}, B_{\perp} = 1300 \text{ m}$$

## Master Selection: $\sum$ Correlation $\rightarrow$ max ?

- Standard deviations of the delays per acquisition
- RMS values of the difference maps MERIS minus InSAR
- Correlation between InSAR and MERIS

## Master Selection: $\Sigma$ Correlation $\rightarrow$ max ?

- Standard deviations of the delays per acquisition
- RMS values of the difference maps MERIS minus InSAR
- Correlation between InSAR and MERIS

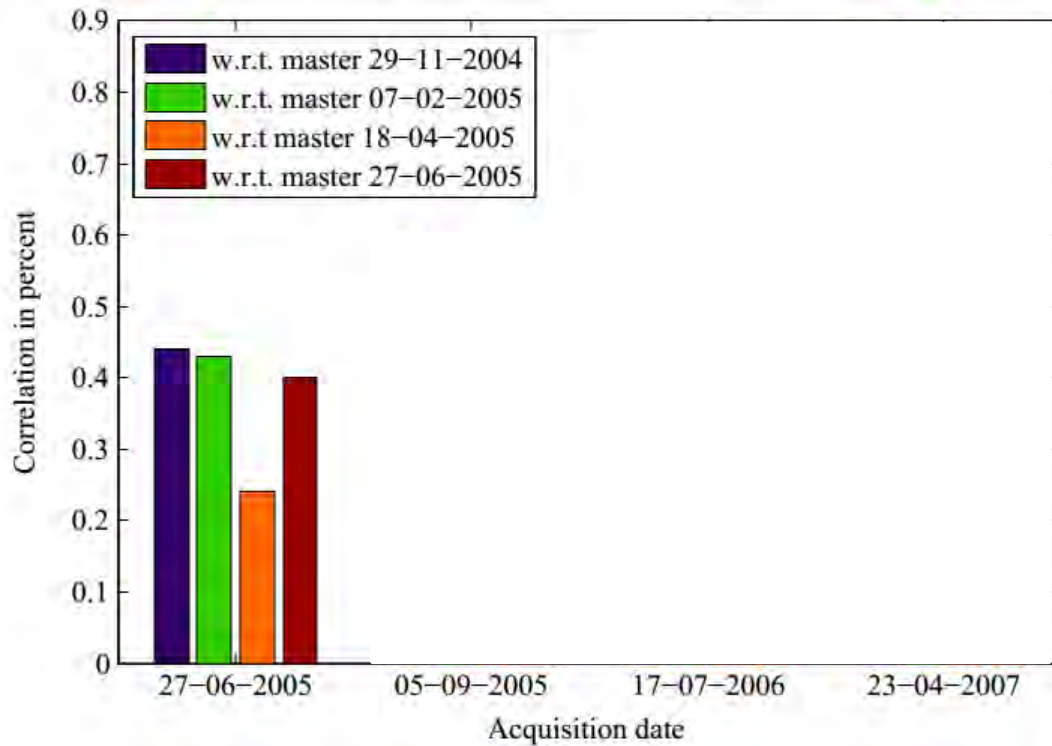
Hooper  
~~1. 18-04-2005~~  
2. 29-11-2004



Hooper  
~~1. 18-04-2005~~  
2. 29-11-2004

## Master Selection: $\Sigma$ Correlation $\rightarrow$ max ?

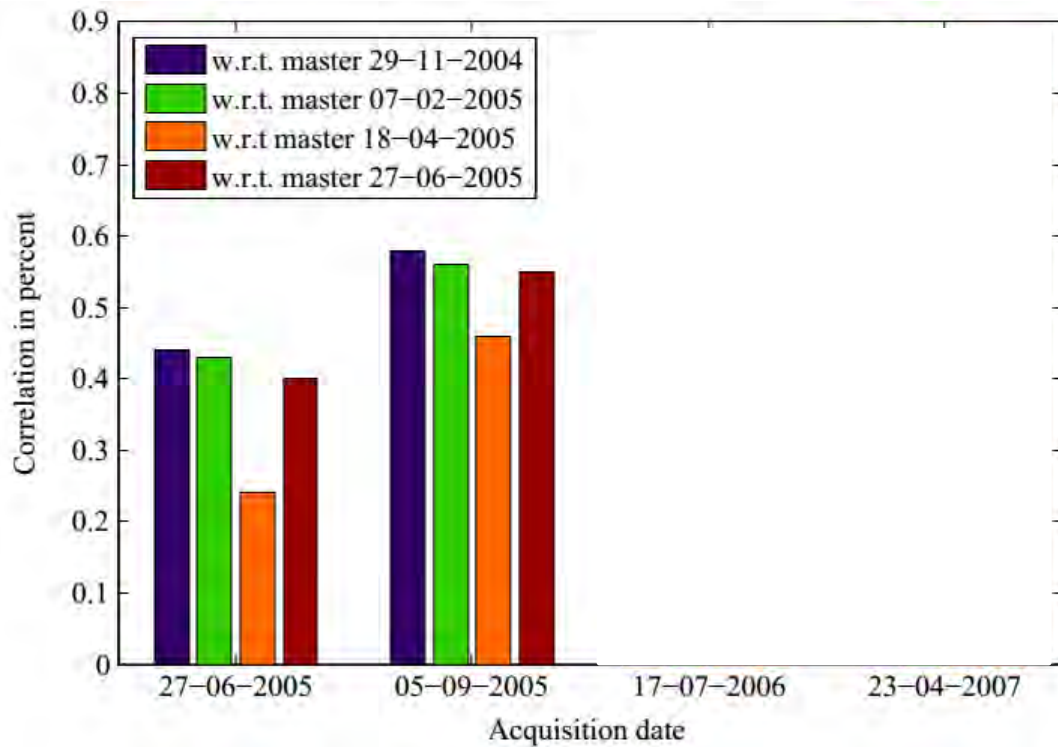
- Standard deviations of the delays per acquisition
- RMS values of the difference maps MERIS minus InSAR
- Correlation between InSAR and MERIS



Hooper  
~~1. 18-04-2005~~  
2. 29-11-2004

## Master Selection: $\Sigma$ Correlation $\rightarrow$ max ?

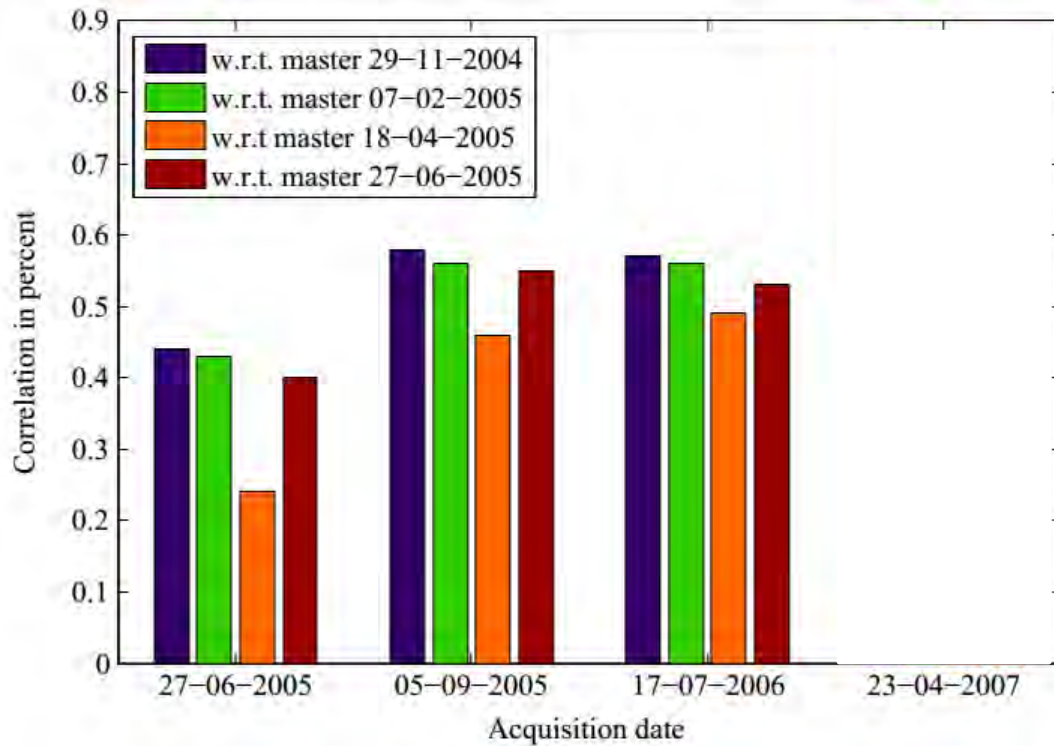
- Standard deviations of the delays per acquisition
- RMS values of the difference maps MERIS minus InSAR
- Correlation between InSAR and MERIS



Hooper  
~~1. 18-04-2005~~  
 2. 29-11-2004

## Master Selection: $\Sigma$ Correlation $\rightarrow$ max ?

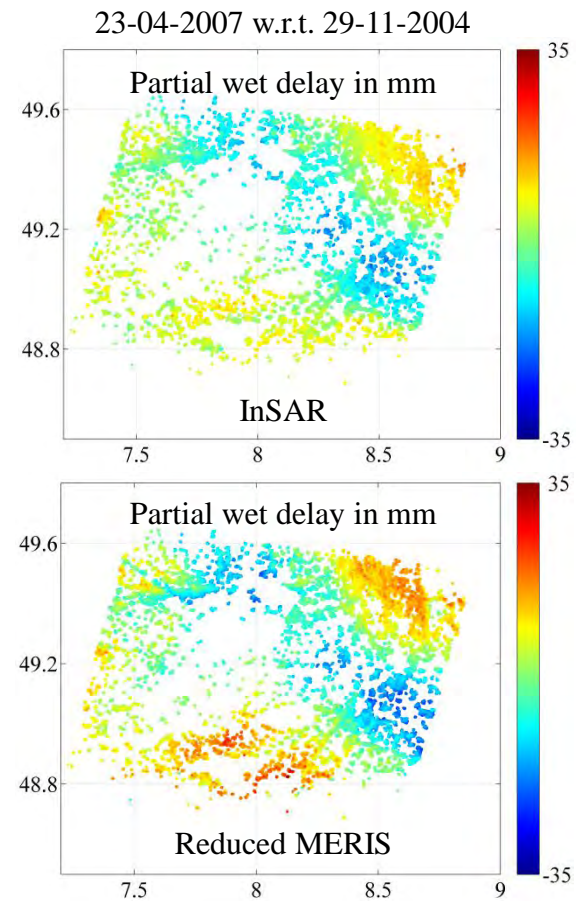
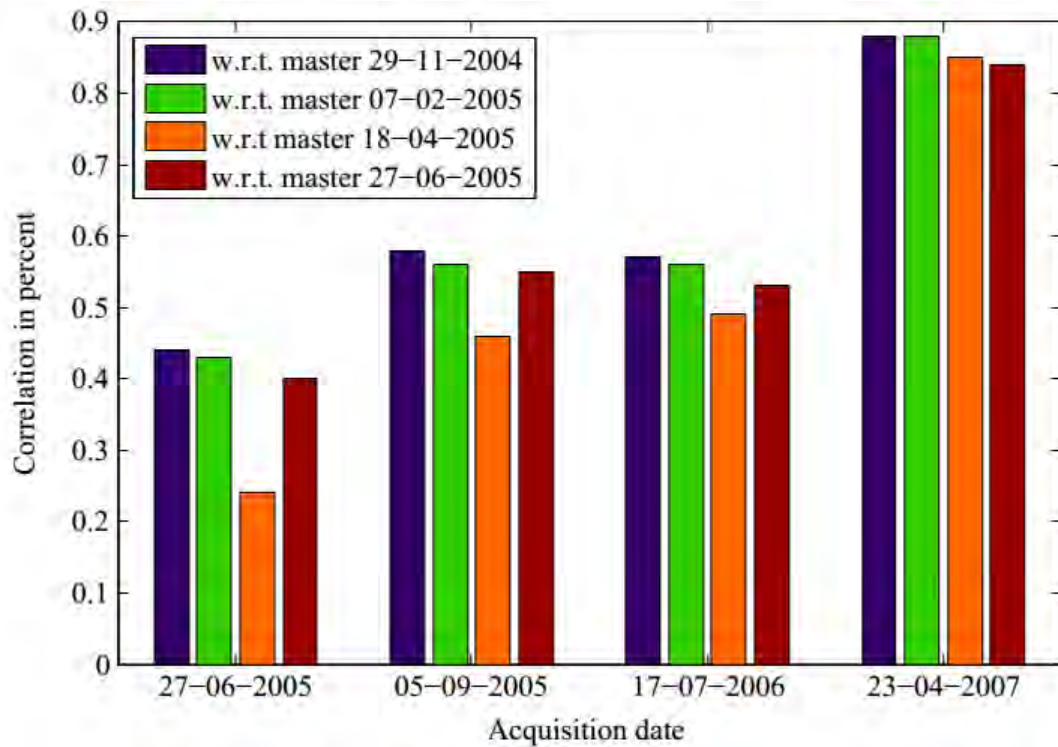
- Standard deviations of the delays per acquisition
- RMS values of the difference maps MERIS minus InSAR
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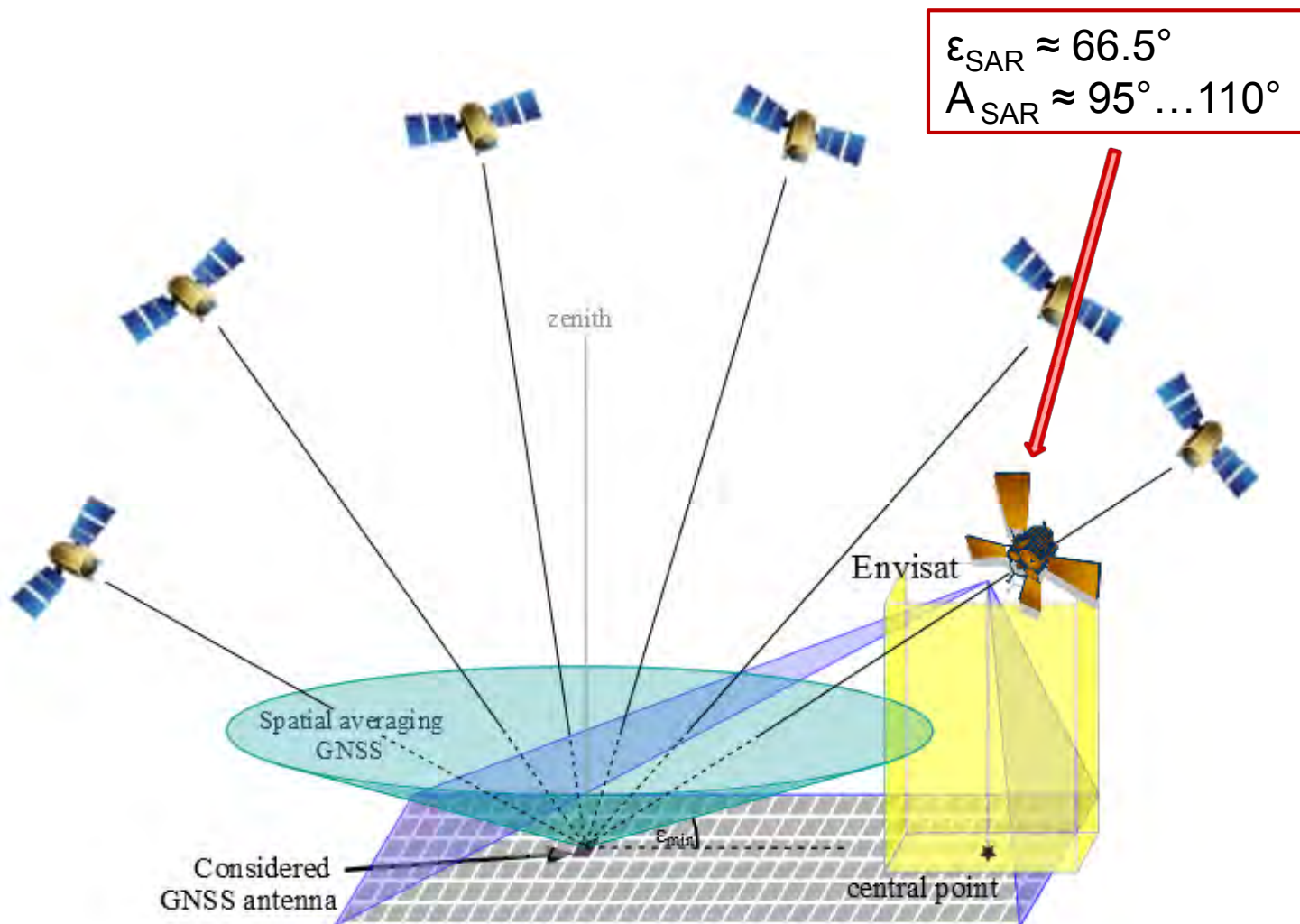
# Master Selection: $\Sigma$ Correlation $\rightarrow$ max ?

**Hooper**  
~~1. 18-04-2005~~  
 2. 29-11-2004

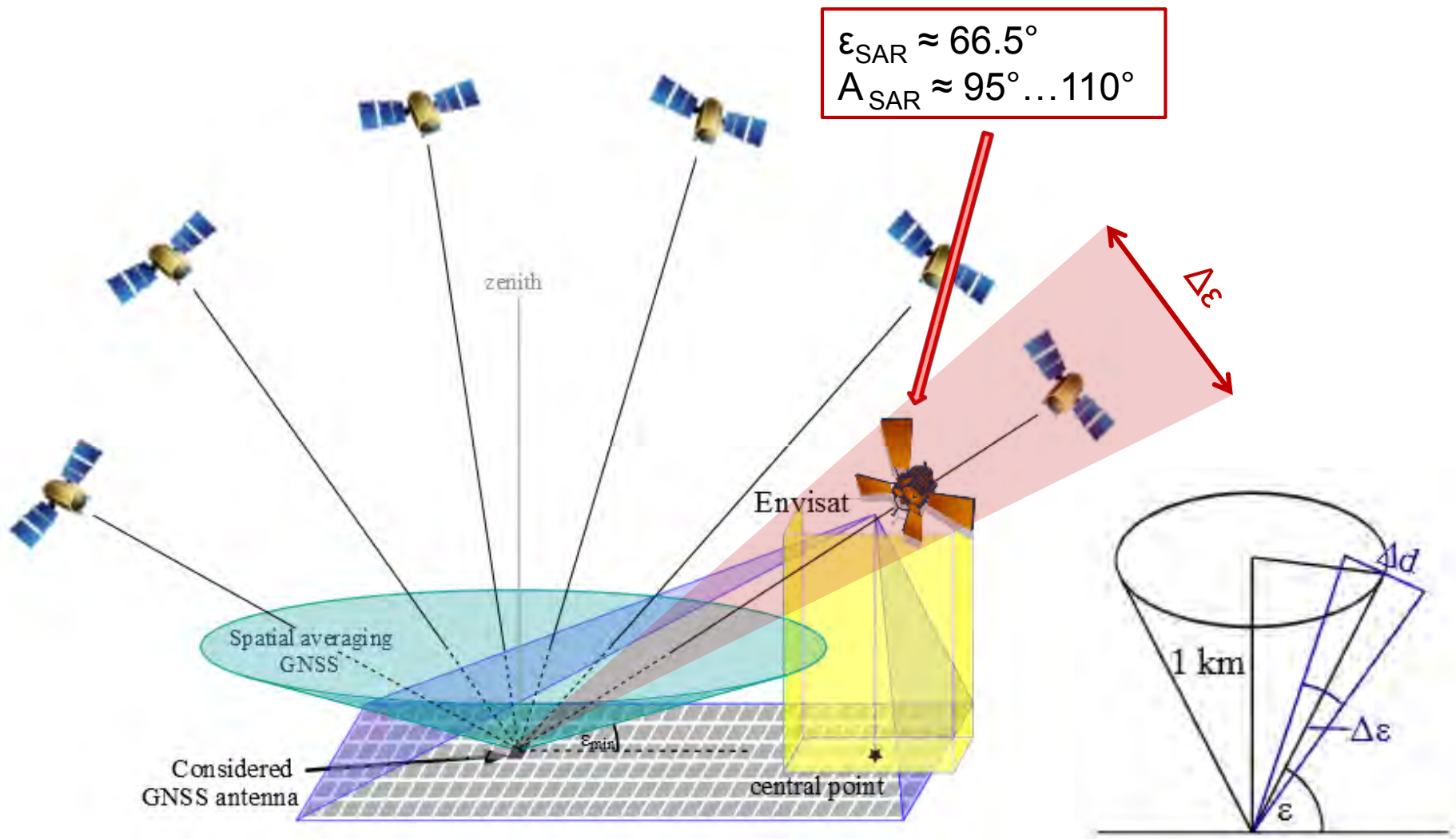
- Standard deviations of the delays per acquisition
- RMS values of the difference maps MERIS minus InSAR
- Correlation between InSAR and MERIS



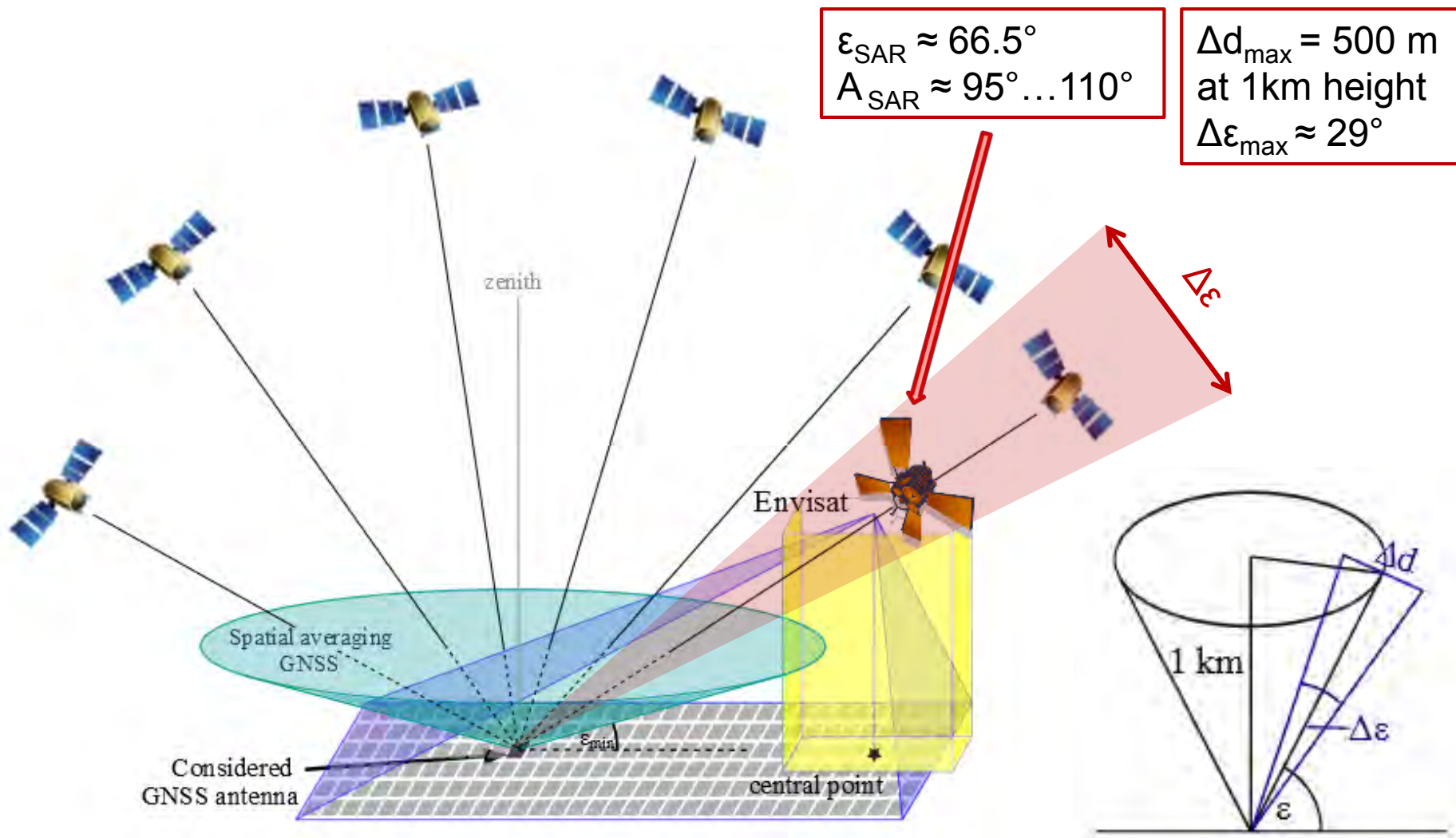
# Finding “Close” Satellites



# Finding "Close" Satellites

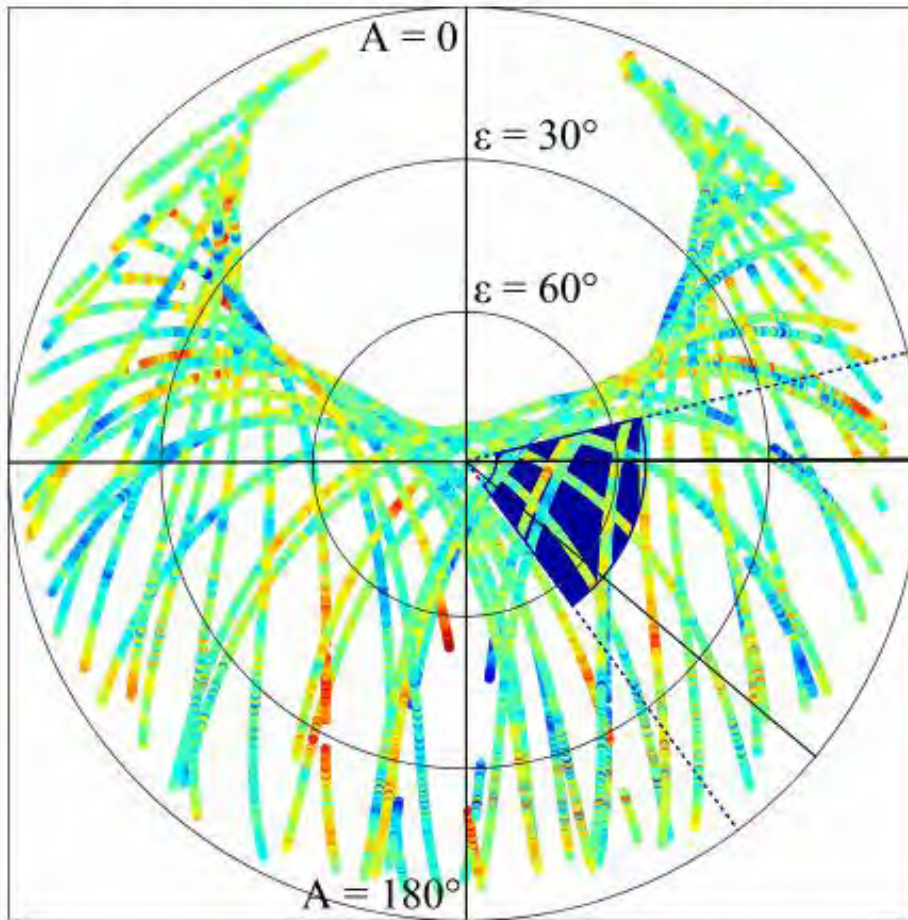


# Finding “Close” Satellites



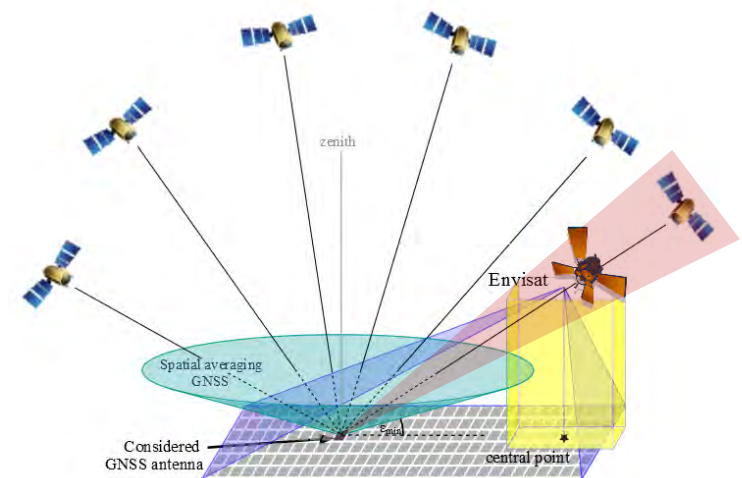
# Finding “Close” Satellites

Heidelberg (0387), GPS satellites on 27-06-2005



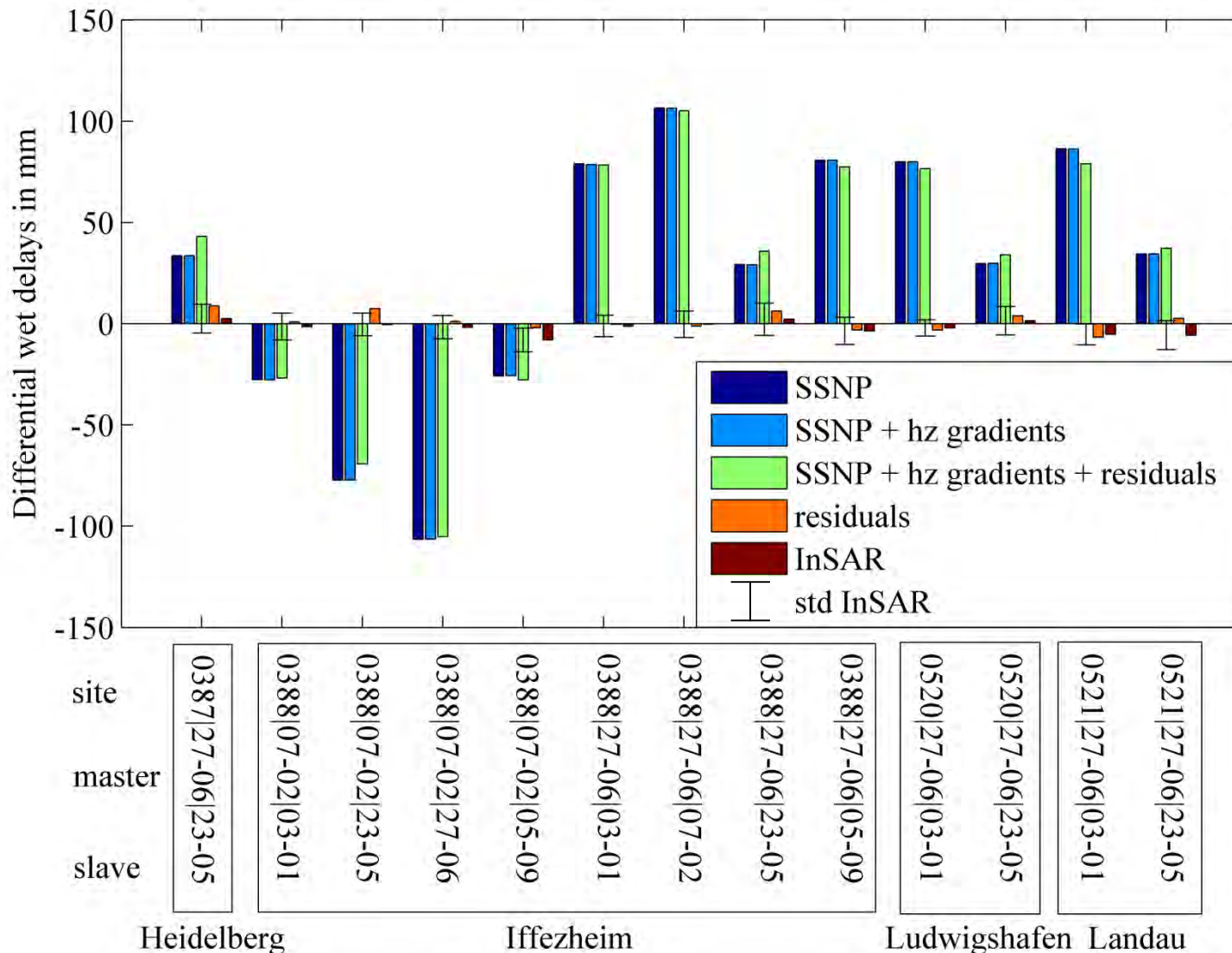
## Search window

- Azimuth and elevation:  $29^\circ$
- Time: 1 minute



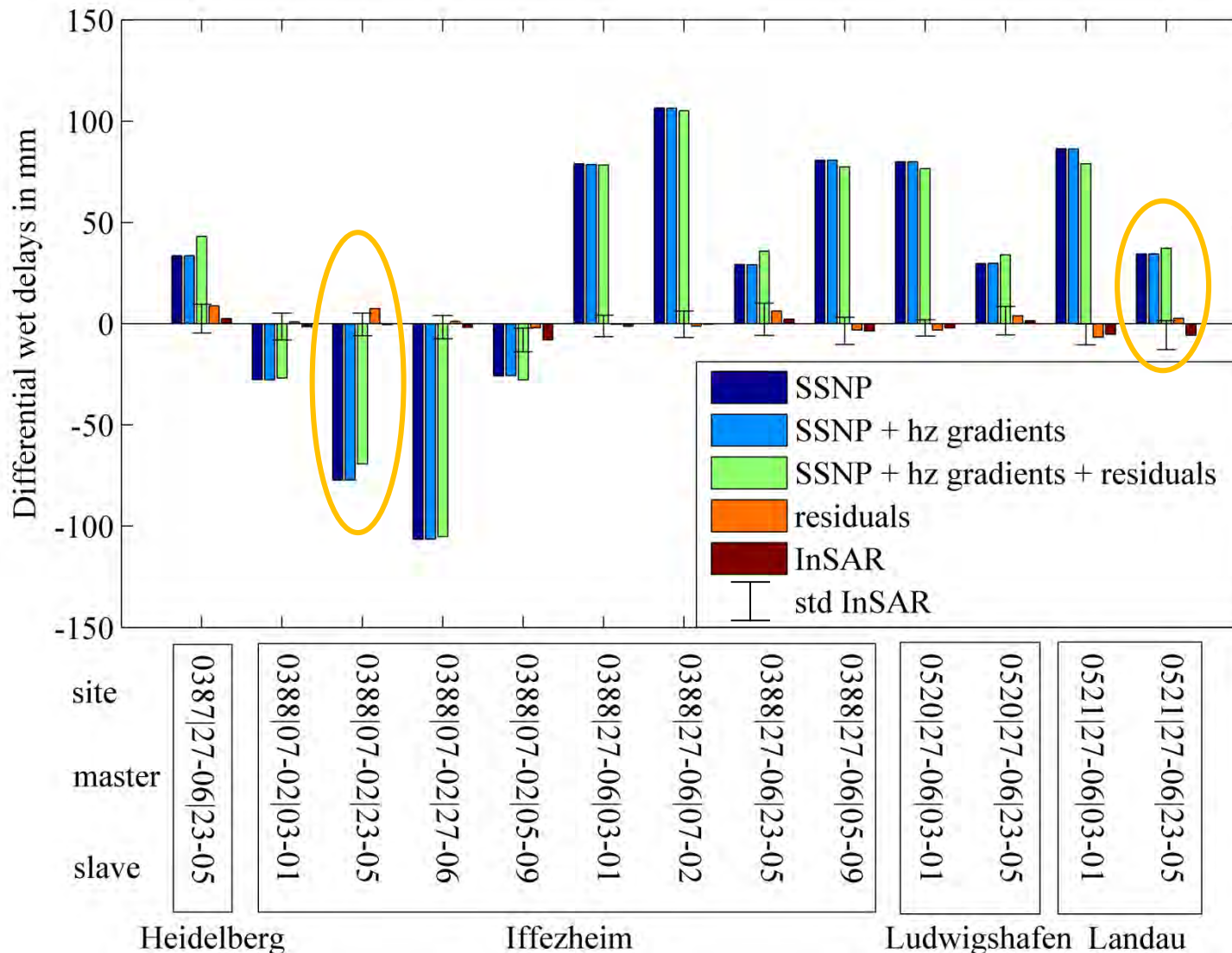


# Satellite-Directed Comparison of the Delays



- **SSNP:** important
- **Residuals:** important
- **Horizontal gradients:** negligible
- GNSS:** wet delay differences
- InSAR:** short-scale wet delay differences

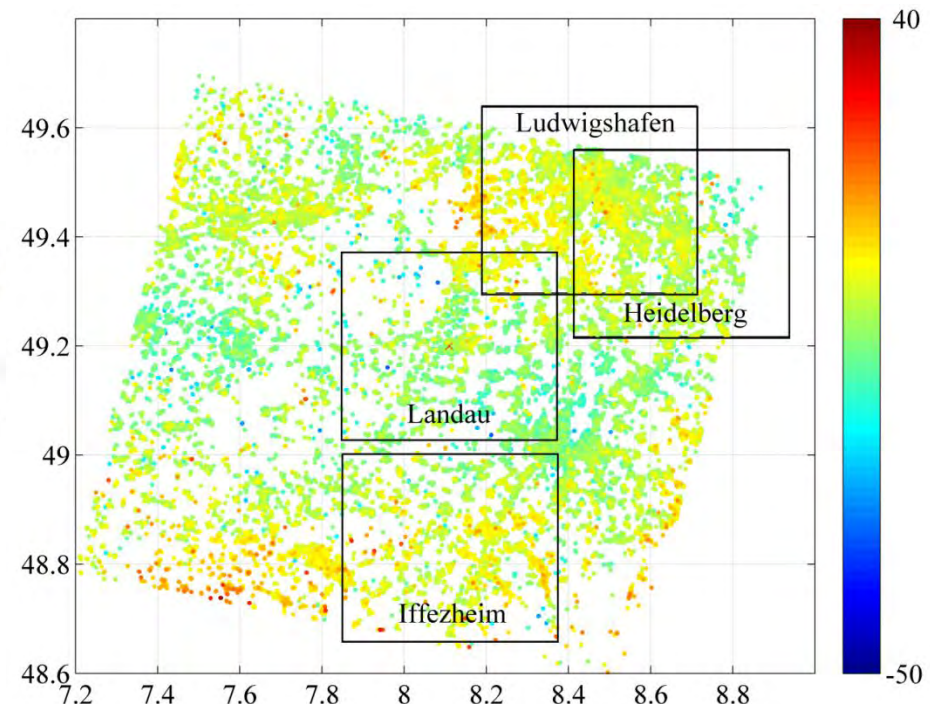
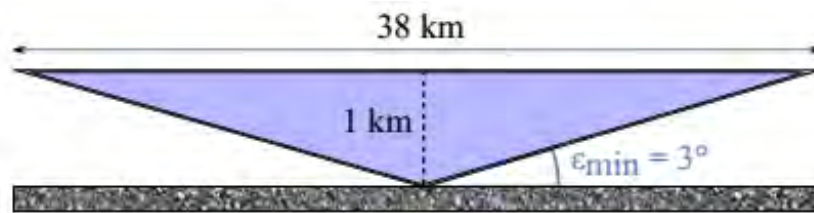
# Satellite-Directed Comparison of the Delays



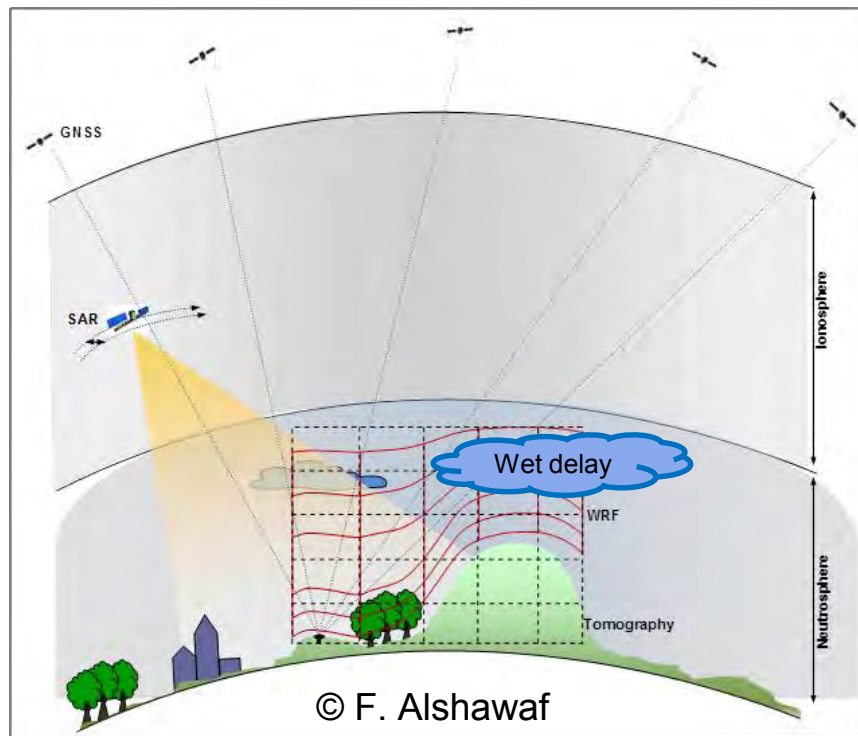
- SSNP: important
- Residuals: important
- Horizontal gradients: negligible
- GNSS: wet delay differences
- InSAR: short-scale wet delay differences

## Conclusion and Outlook of the Master Thesis

- Assumptions within GNSS observations:
  - No site-specific effects (MP, antenna) → Residual stacking?
  - Anisotropy of the residuals → Water vapor ✓
- Topography-dependent component and linear trend → Importance?
- Spatial averaging → Effect on comparison?



## Conclusion and Outlook of the Master Thesis



- More GNSS observing sites
- More SAR acquisitions
- WRF
- Tomography?

- Enhanced master selection for water vapor retrieval; based on
  - Hooper's approach
  - External information
- InSAR water vapor maps
  - Difference maps
  - Partial nature
- Phase residuals:
  - Anisotropic component of the wet delay deduced from GNSS
- Combination of the assets of each data set

Thank you for your attention.



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