

# Lake level variations from satellite radar altimetry with retracking of multi-leading edge

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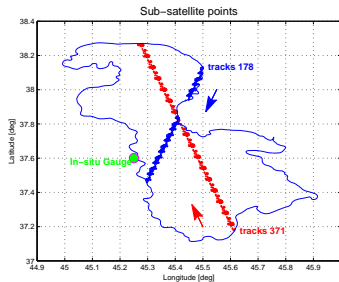
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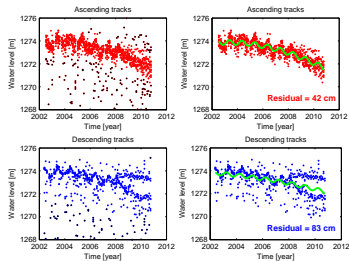
GIS

# Why waveform retracking?

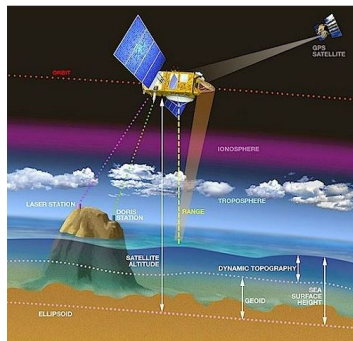
- ▶ Improve the quality of water level measurements
- ▶ Increase the number of reliable observations particularly in the shoreline and shallow water



Water level time series and fitting the trend to the all values



# RADAR principle



<http://www.altimetry.info>

# How can we have more precise water level measurements?

- ▶ Increasing precision of range measurements
  - ▶ Use more precise range correction, e.g. corrections included in GDRs
  - ▶ *waveform retracking, i.e. calculate another range correction from SGDRs*

$$\Delta R_{\text{retracking}} = (G_r - G_0) \times \frac{c}{2} \tau$$

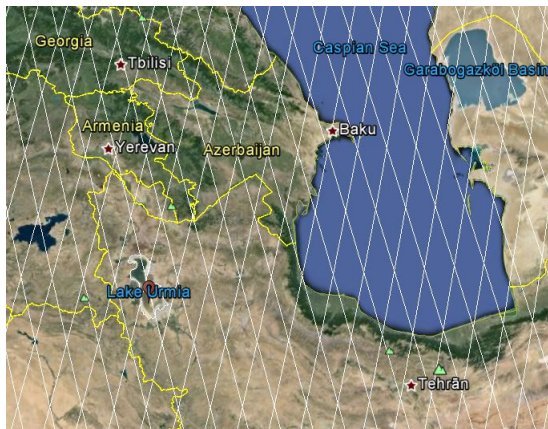
$G_r$ : retracked gate,  $G_0$ : nominal retracking gate,  $c$ : light velocity,  $\tau$ : pulse duration

# Waveform retracking techniques

- ▶ Conventional retrackers
  - ▶ Onboard retracker (Ice-1/2 and Sea-ice)
  - ▶ Offset Center Of Gravity (OCOG)
  - ▶ Threshold
  - ▶  $\beta$ - parameters
- ▶ Unconventional retrackers
  - ▶ Multi-leading edge
  - ▶ Modified waveform

## Data and area of study

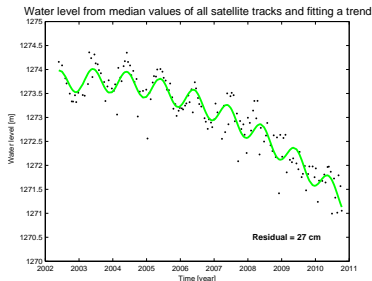
RA2 Geophysical and Sensor Data Records, i.e. RA2 GDRs and RA2 SGDRs of Envisat satellite altimetry from cycle 6 to cycle 113



Envisat satellite ground tracks from cycle 92

# Conventional retrackerers

- ▶ Onboard retrackerers:  
Water level from RA2 GDRs data using median values of water level in each satellite over pass in Ice-1 retracker algorithm

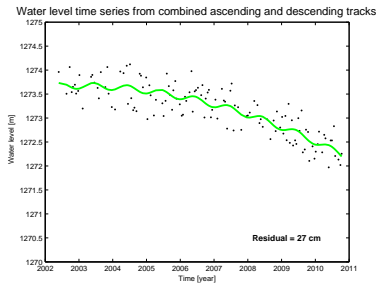


$$h(t_i) = a + bt_i + ct_i^2 + d \sin\left(\frac{2\pi}{T} t_i\right) + e \cos\left(\frac{2\pi}{T} t_i\right)$$

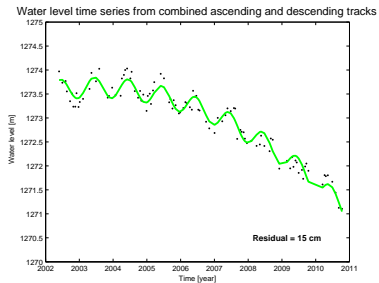
$a$ ,  $b$ ,  $c$ ,  $d$  and  $e$  are unknown parameters to be estimated.  $T$  is the annual period and  $h$  is the observed water height.

# Conventional retrackerers

## ► OCOG



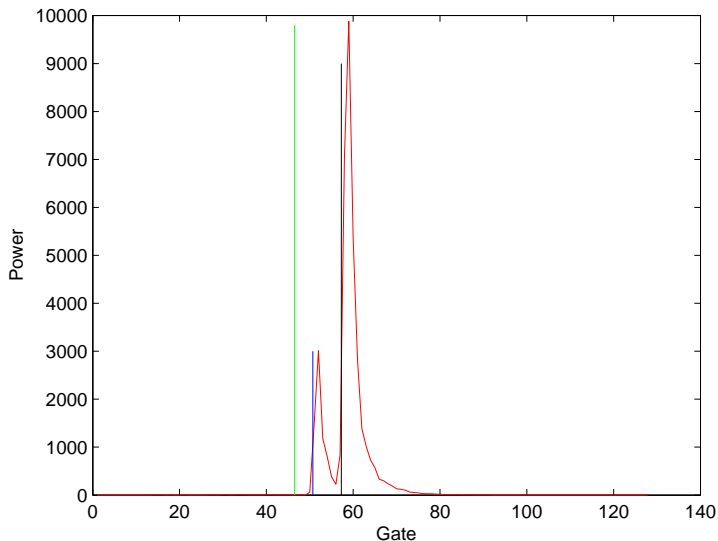
## ► Threshold





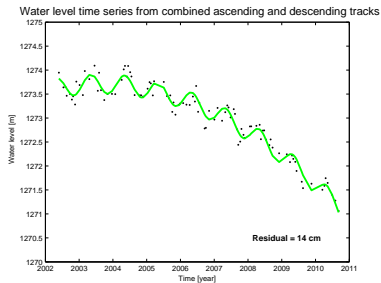
# Unconventional retrackers

- ▶ Multi-leading edge



# Unconventional retrackerers

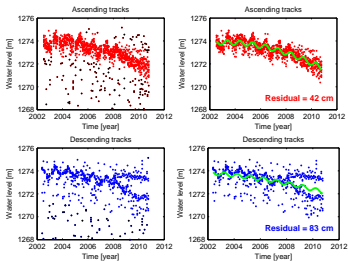
- ▶ Multi-leading edge



# Comparing different retracker

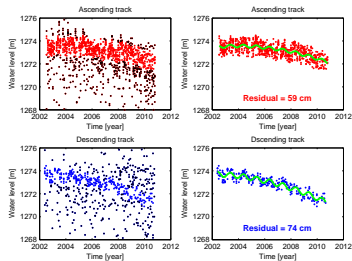
## ► Onboard retracker

Water level time series and fitting the trend to the all values



## ► Other retracker

Water level time series based on Threshold 10 % retracker



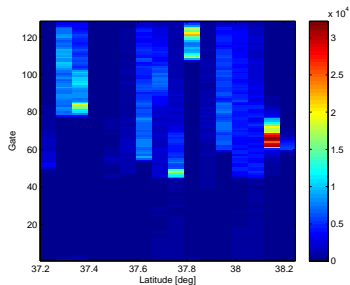
# Comparing different retrackerers

Water level standard deviation from different retrackerers		
retracker	standard deviation (cm)	improvement
Ice-1	27	–
OCOg	27	0 %
Threshold 10	18	33 %
Threshold 20	15	44 %
Threshold 50	17	37 %
Multi-leading edge	14	48 %

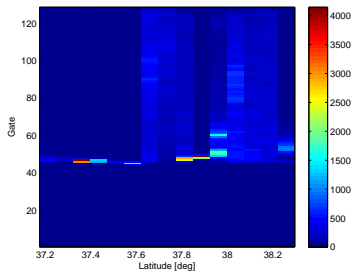
$$Improvement = \frac{\sigma_{Ice-1} - \sigma_{Ret}}{\sigma_{Ice-1}} \times 100 \%$$

# Along track waveform variations

First ascending pass-Jun 2002

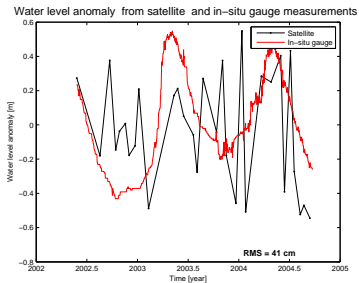


Last ascending pass- Sep 2010

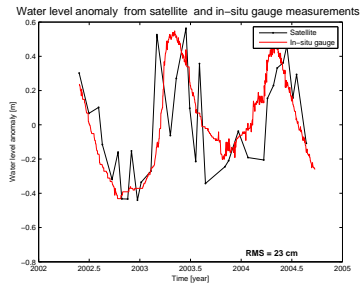


# Validation

## ► OCOG

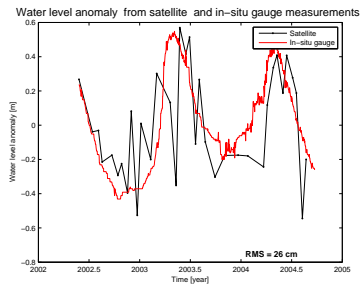


## ► Threshold



# Validation

## ► Multi-leading edge



# Conclusion

- ▶ Obviously waveform retracking techniques can improve the quality of altimetry data.
- ▶ Due to the land and environmental effects on the return echoes to the altimeter particularly in the shoreline the waveform retracking is necessary.
- ▶ The quality of water level is dependent on the waveform retracking techniques.
- ▶ According to the result of data processing using both RA2 GDR and RA2 MWS (SGDRs) of Envisat, multi-leading edge and threshold 20 % retrackers outperform the other retrackers to determine water level variations of Urmia lake.



# Works under way

- ▶ Continuing waveform retracking using:
  - ▶  $\beta$ -parameter
  - ▶ Modified waveform

**Thank you for your attention**