

Global Gravity Field Determination from Future Satellite-Gravimetric Missions analysed by IGG and GFZ

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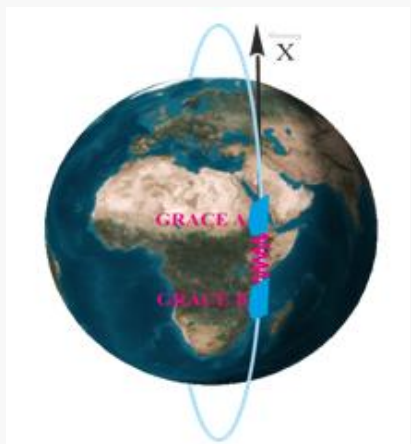
2- German Research Centre for Geosciences – GFZ, Potsdam,
Germany.

Geodetic Week, 09-11.10.2012, Hannover, Germany



- **Simulated mission configurations**
- **Models used for the simulations**
- **Simulated data and errors used for simulation scenarios**
- **Results in the spectral domain**
- **Results in the spatial domain**
- **Summary**

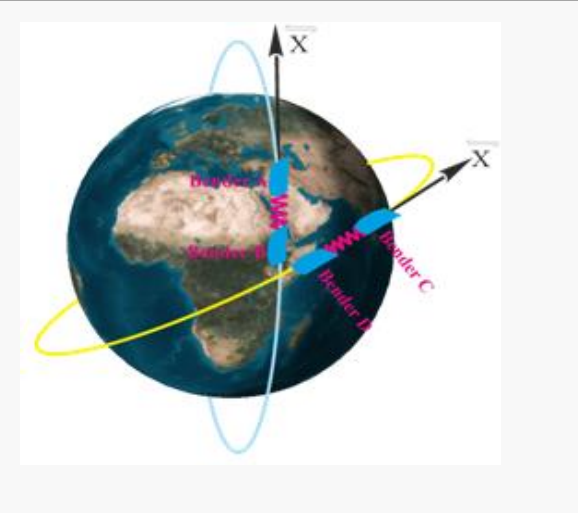
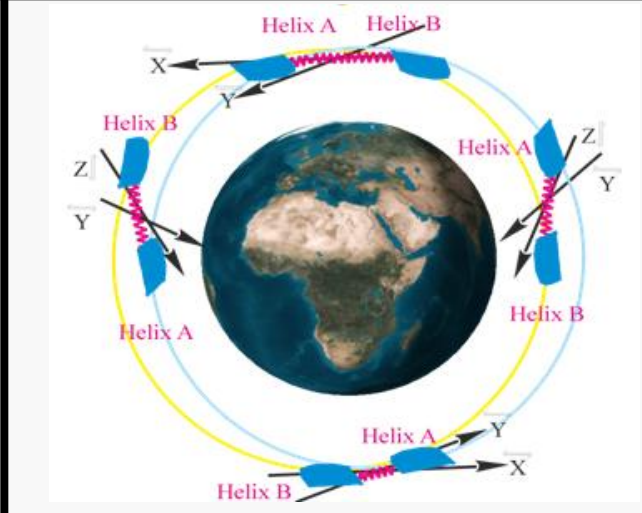
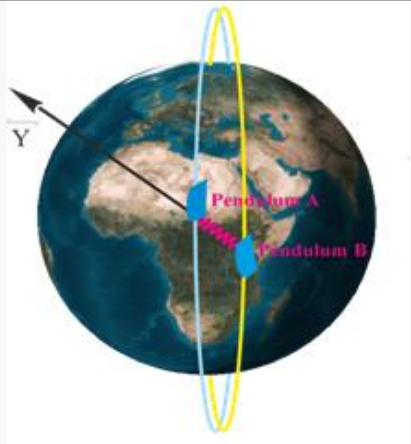
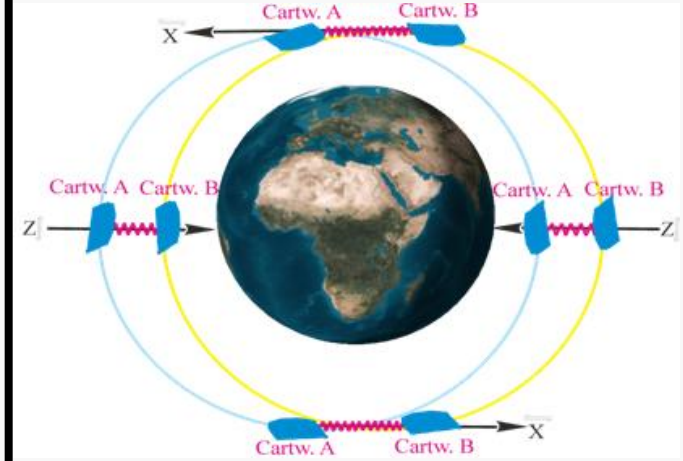
GRACE ($\rho_x = 220$ km)



(Alternative) GRACE-FO ($\rho_{x,y} = 220/25$ km)



Cartwheel ($\rho_{x,z} = 100/50$ km)



3 Pendulum formations

Pendulum ($\rho_{x,y} = 96/43$ km)

Pendulum V1 ($\rho_{x,y} = 166/166$ km)

Pendulum V2 ($\rho_{x,y} = 83/83$ km)

Helix ($\rho_{x,y,z} = 50/150$ km)

Bender ($\rho_x = 100$ km)

- 7 possible future missions are investigated plus GRACE as reference
- 6 missions were treated as drag-free but for GRACE and GRACE-FO non conservative forces were considered.
- It was decided that GFZ will provide IGG with orbits, SST data, accelerometer and star-trackers data.
- The simulation period was set to 32 days corresponding to the repeat cycle for an altitude of 335km.
- The integration step-size was set to 5 seconds
- GFZ-EPOS and IGG-GROOPS softwares have been used to estimate the gravity field solutions (up to d/o 120)

- **Static gravity field model EIGEN-GL04C**
 - **Time-variable background model AOHIS ESA Model Version 2**
 - **Ocean tides model EOT08a (Q1,O1,P1,K1,M2,N2,K2,S2) up to 50x50**
 - **Planetary ephemerides: DE405 (only Sun and Moon)**
 - **Permanent tide: C20 from EIGEN-GL04C**
 - **Models for non-gravitational forces (transformed to acc. data)**
 - **air drag, solar radiation pressure, albedo.**
 - **no precession, no nutation, no polar motion**
 - **Simple Earth rotation only by**
- $$\theta = 2 \pi (0.7790572732640 + 1.00273781191135448 (\text{MJDUTC} - 51544.5))$$
- **no Earth tides model, no pole and ocean tide models,**
 - **no relativity**

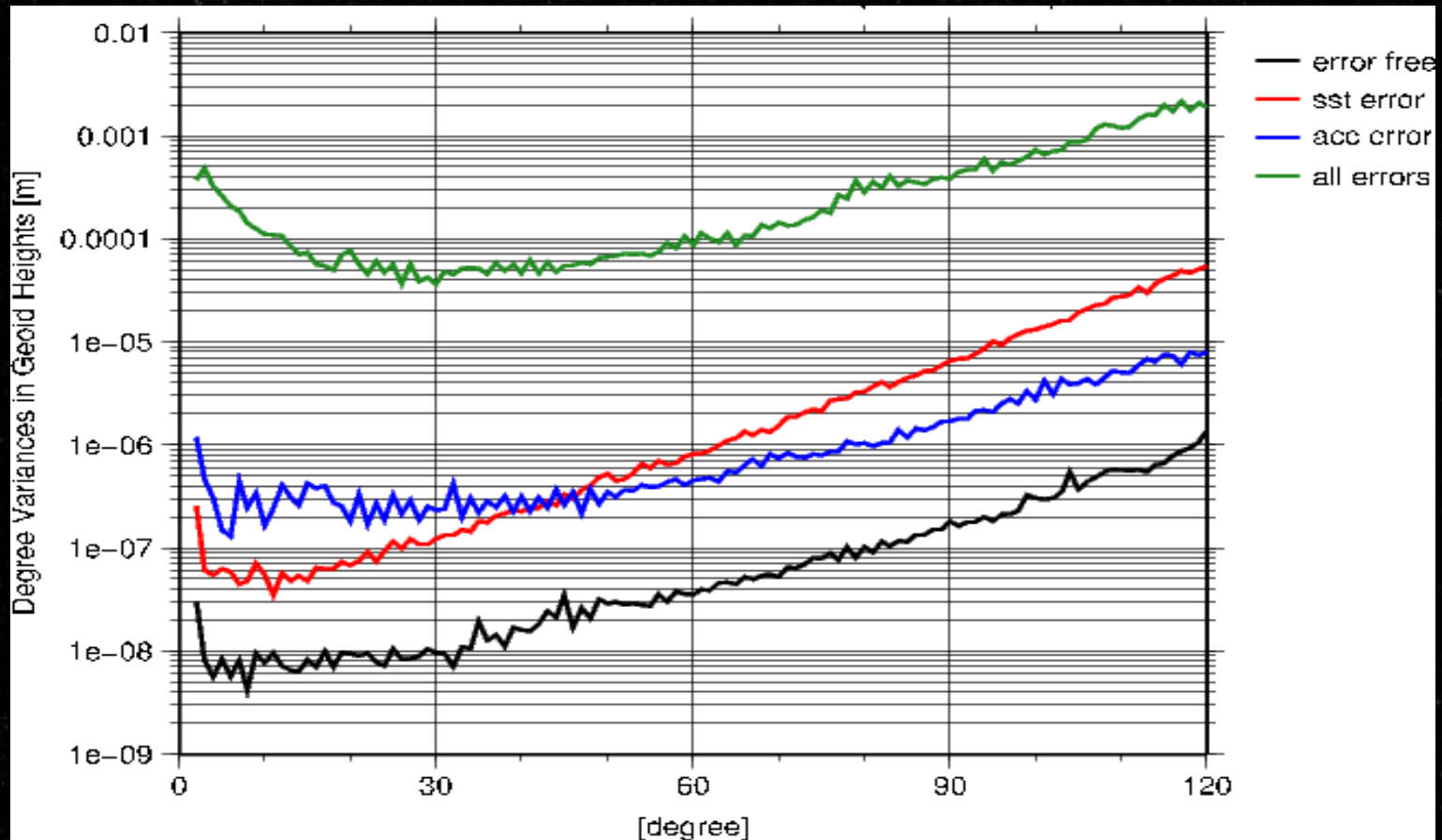


- **Simulated Data:**
 - **SST range-rate observations**
 - **GPS to LEO satellites observations (code + phase)**
 - **Accelerometer data for the non-drag free missions**
 - **Star-trackers data**

- **Simulated Errors :**
 - **SST observations: colored noise from ife-iFR**
 - **Accelerometer data: colored noise from ife-iFR**
 - **No orbit error was introduced**

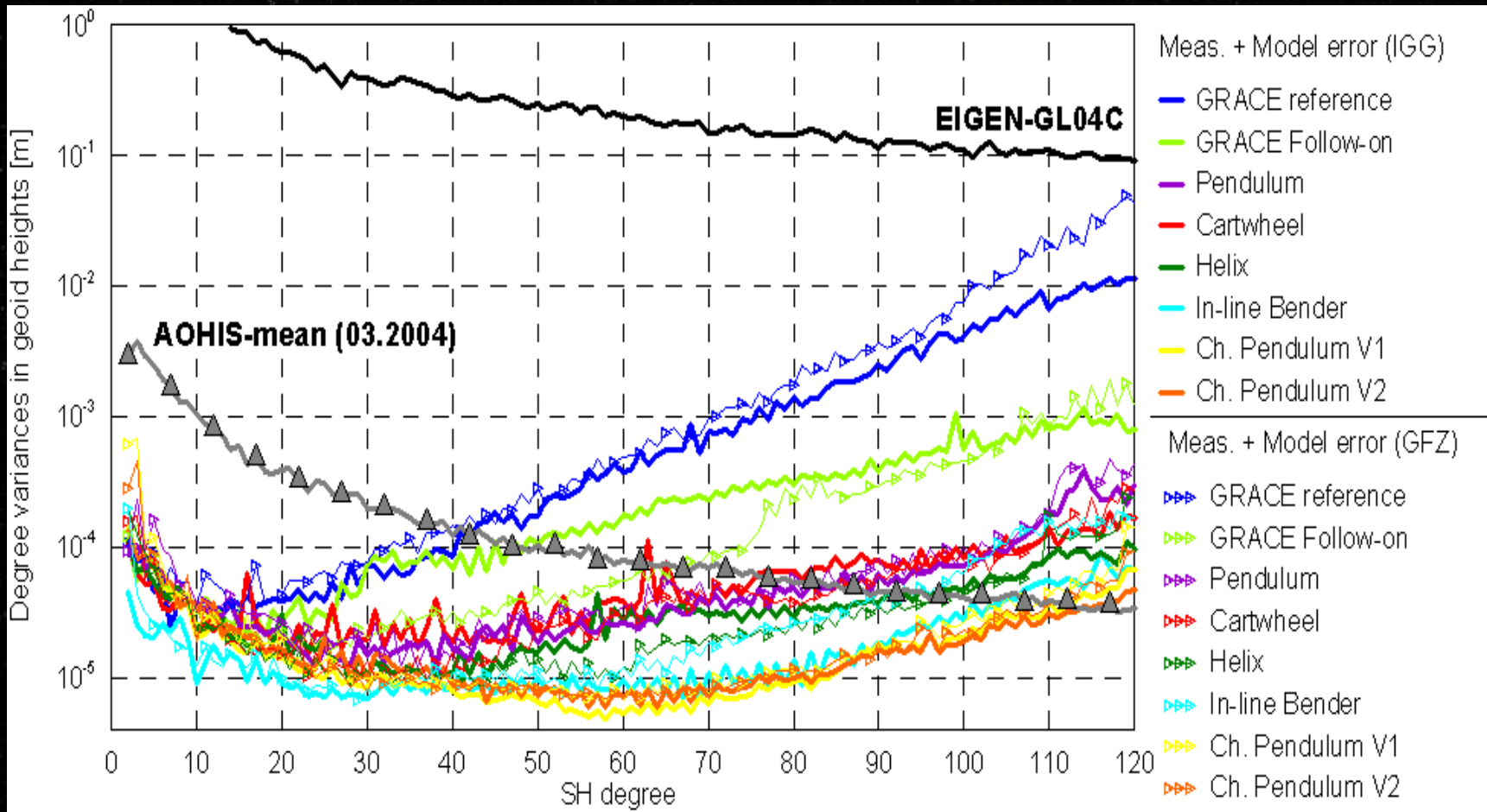
- **The GFZ simulations are based on the GFZ EPOS software:**
 - Package operated with a symmetric Adams-Cowell integrator of order seven
 - Using the full dynamical approach
- **The IGG simulations are made with the IGG GROOPS software:**
 - Package procedure is based on the solution of Newton's equation as
 - Solution of a boundary value problem (Fredholm integral equation of the second kind).
 - 35 minutes arcs are used to compute observation equations and normal equations

Different error influences on (**alternative**) GRACE-FO (GFZ-EPOS)

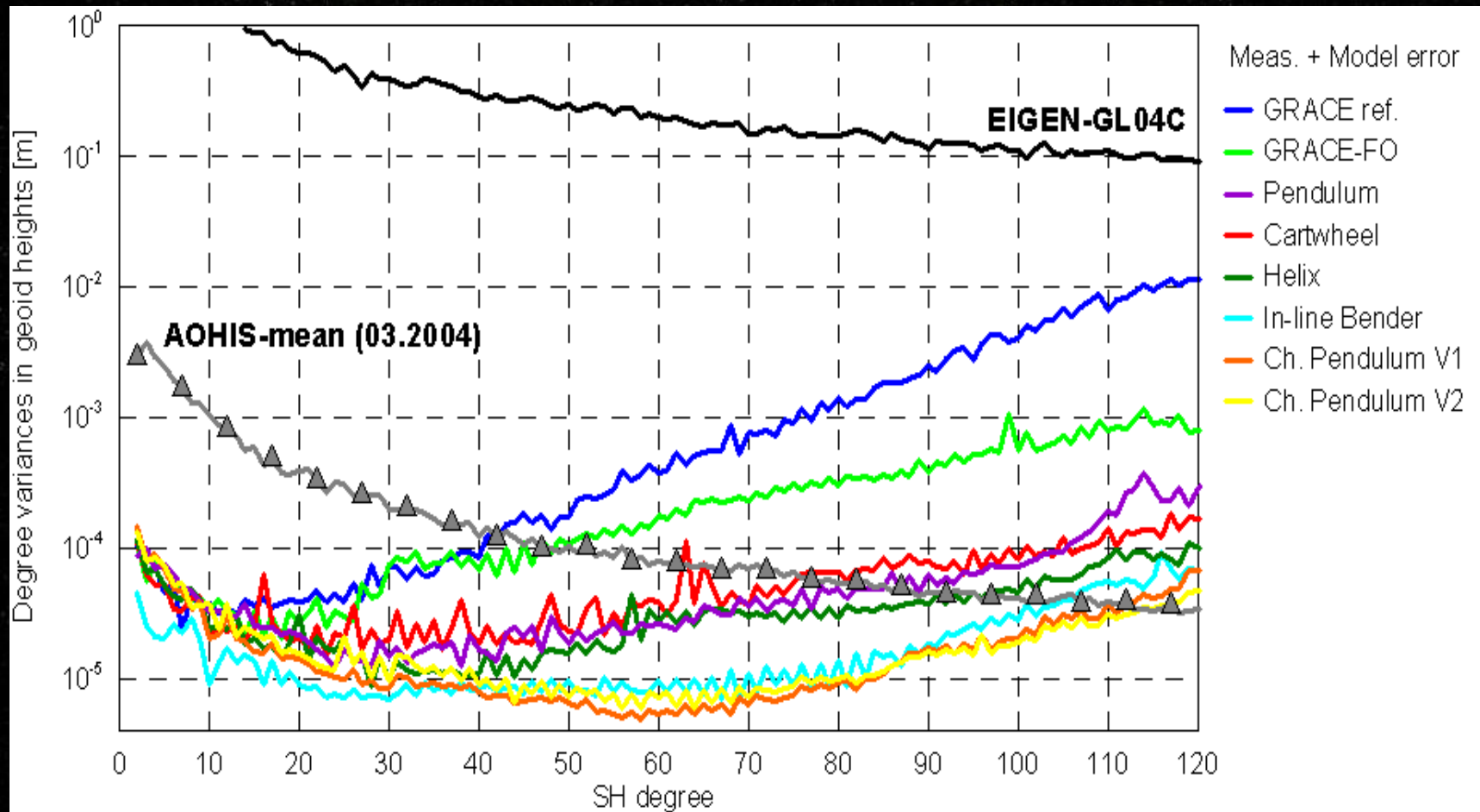


Comparison of the Results between IGG and GFZ

Agreement of current results by 120x120

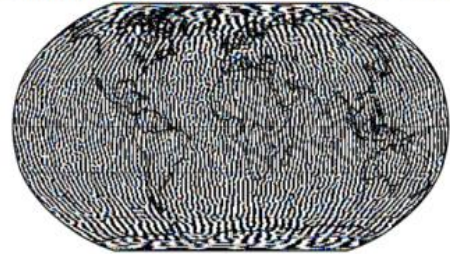


IGG Results – Spectral domain

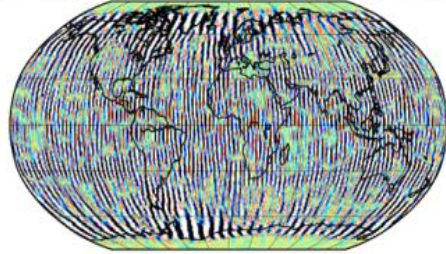


IGG-GROOPS

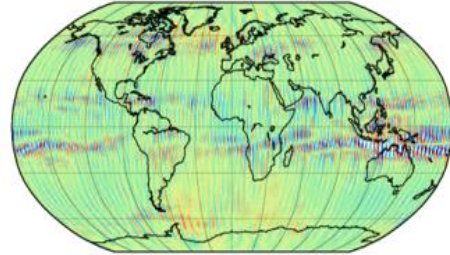
GRACE reference (min.= -209.18, max.= 216.67, RMS= 43.605) GRACE Follow-on (min.= -37.756, max.= 38.096, RMS= 5.14023)



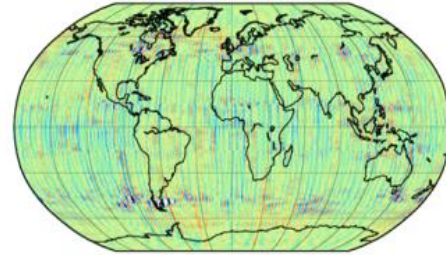
Pendulum (min.= -7.84989, max.= 9.39005, RMS= 1.06742)



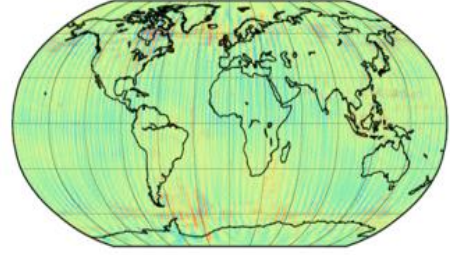
Cartwheel (min.= -7.1101, max.= 8.2585, RMS= 0.82904)



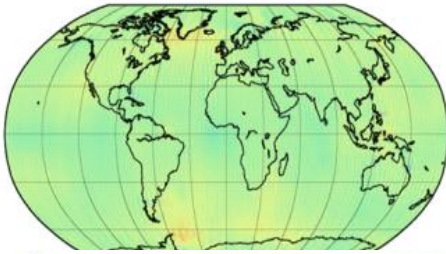
Helix (min.= -3.58067, max.= 4.01495, RMS= 0.53023)



In-line Bender (min.= -2.2531, max.= 2.2576, RMS= 0.30911)



Ch. Pendulum V1 (min.= -2.45107, max.= 1.1918, RMS= 0.2929) Ch. Pendulum V2 (min.= -1.6051, max.= 1.3775, RMS= 0.25468)

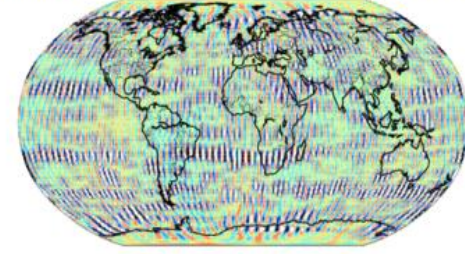


GFZ-EPOS

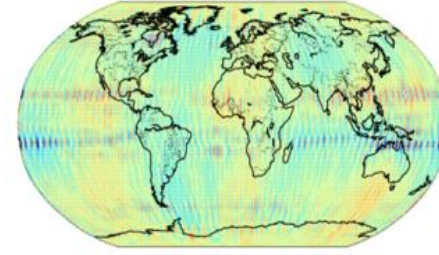
GRACE reference (min.= -642.19, max.= 600.05, RMS= 114.025) GRACE Follow-on (min.= -29.9503, max.= 33.2638, RMS= 4.8256)



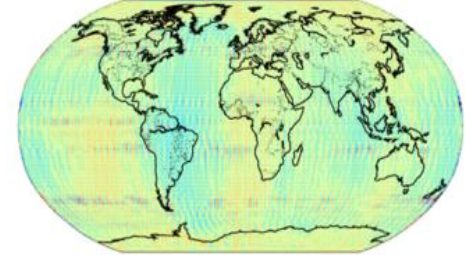
Pendulum (min.= -11.3675, max.= 9.6287, RMS= 1.3419)



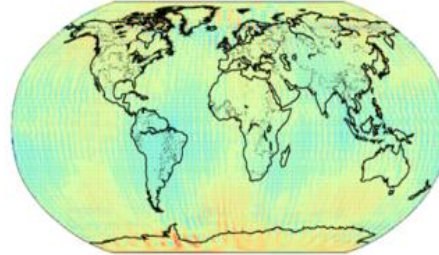
Cartwheel (min.= -5.1096, max.= 5.2585, RMS= 0.7837)



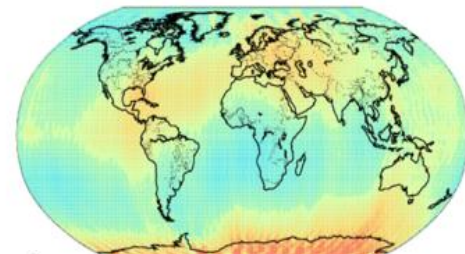
Helix (min.= -3.2281, max.= 3.0341, RMS= 0.5725)



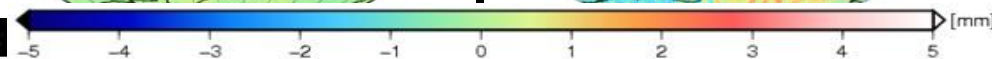
In-line Bender (min.= -4.1122, max.= 4.0196, RMS= 0.6199)



Ch. Pendulum V1 (min.= -3.4138, max.= 4.1196, RMS= 0.7948)



Ch. Pendulum V2 (min.= -1.7105, max.= 3.0416, RMS= 0.5001)



- Within the frame of future gravity missions project, 8 Basic-formations are investigated.
- Full-scale mission are carried out using two different softwares of GFZ (EPOS) and IGG (GROOPS).
- Generally good agreement in the spectral domain between the EPOS and GROOPS solutions but for a few missions (GRACE, Bender) some discrepancies for $d/o > 90$.
- It has been found that the aliasing effects are so far the main problem that future missions will face, especially for the GRACE Follow-on configuration.
- Simulations show obvious potential improvements for the (alternative) GRACE-FO formation w.r.t. the GRACE reference.
- Most promising for a future gravity mission (2020+) seems the Bender constellation.

Thank you
for your attention